



Warped Product Submanifolds of Kaehler Manifolds with Pointwise Slant Fiber

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Abstract. It was shown in [15, 16] that there does not exist any warped product submanifold of a Kaehler manifold such that the spherical manifold of the warped product is proper slant. In this paper, we introduce the notion of warped product submanifolds with a slant function. We show that there exists a class of non-trivial warped product submanifolds of a Kaehler manifold such that the spherical manifold is pointwise slant by giving an example and a characterization theorem. We also prove that if the warped product is mixed totally geodesic then the warping function is constant.

1. Introduction

In [8], B.-Y. Chen and O.J. Garay introduced the notion of pointwise slant submanifolds of an almost Hermitian manifold and they have obtained many interesting result and gave a method how to construct such submanifolds in Euclidean space. They defined these submanifolds as follows: For any non-zero vector $X \in T_pM$, $p \in M$, the angle $\theta(X)$ between JX and the tangent space T_pM is called the *Wirtinger angle* of X . The Wirtinger angle gives rise a real-valued function $\theta : TM - \{0\} \rightarrow \mathbb{R}$, called a *wirtinger function*, defined on the set $T^*M = TM - \{0\}$ consisting of all nonzero vectors on M . A submanifold M of an almost Hermitian manifold \tilde{M} is called *pointwise slant* if, at each point $p \in M$, the Wirtinger angle $\theta(X)$ is independent of the choice of the nonzero tangent vector $X \in T_pM$. In this case, θ can be regarded as a function on M , which is called the *slant function* of the pointwise slant submanifold. We note that the pointwise slant submanifolds have been studied in [11] by F. Etayo under the name of quasi-slant submanifolds. We also note that every slant submanifold is pointwise slant but converse may not be true. These submanifolds are also studied in [14].

On the other hand, the geometry of warped product submanifolds became an active field of research after Chen's papers on the geometry of warped product CR-submanifolds [4, 5]. He proved that there do not exist warped product submanifolds of the form $M_{\perp} \times_f M_T$ in a Kaehler manifold \tilde{M} . Then he introduced the notion of CR-warped products of Kaehler manifolds as follows: A submanifold of a Kaehler manifold is called the CR-warped product if it is the warped product of the form $M_T \times_f M_{\perp}$, where M_T and M_{\perp} are holomorphic and totally real submanifolds of \tilde{M} , respectively. He obtained several fundamental results

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including, a characterization and a sharp inequality for the squared norm of the second fundamental form $\|h\|^2$. Later on, Sahin [15] proved that there do not exist warped product submanifolds of the form $M_T \times_f M_\theta$ and $M_\theta \times_f M_T$ such that M_T and M_θ are holomorphic and proper slant submanifolds of \tilde{M} , respectively. Using the notion of pointwise slant submanifolds, Sahin introduced pointwise semi-slant submanifolds of Kaehler manifolds and investigated their warped products [17].

Moreover, in [16], Sahin also proved the non-existence of warped product submanifolds $M_\perp \times_f M_\theta$ of a Kaehler manifold \tilde{M} , where M_\perp is a totally real submanifold and M_θ is a proper slant submanifold of \tilde{M} . Then he introduced the notion of hemi-slant warped products $M_\theta \times_f M_\perp$. He provided many examples of such submanifolds and obtained interesting results, including a characterization and an inequality. In this paper, first we define pointwise hemi-slant submanifolds of Kaehler manifolds and then we show that there exists a class of non-trivial warped product submanifolds of the form $M_\perp \times_f M_\theta$ in a Kaehler manifold \tilde{M} such that M_\perp and M_θ are totally real and proper pointwise slant submanifolds of \tilde{M} , respectively. We note that one of the characterization result of such warped products is given in [18] by using different technique. It is also notice that the warped product hemi-slant submanifolds of almost Hermitian manifolds were studied under the name of warped product pseudo-slant submanifolds in [18–20].

As we know that there exist nontrivial warped product submanifolds of the form $M_\theta \times_f M_\perp$ in a Kaehler manifold \tilde{M} such that M_θ is proper slant (see [16]) and if we assume that M_θ is pointwise then the warped product pointwise hemi-slant submanifolds of the form $M_\theta \times_f M_\perp$ is a special case of warped product hemi-slant submanifolds $M_\theta \times_f M_\perp$. Thus, we shall leave this case for the repetition purpose i.e., there is no meaning to study warped product pointwise hemi-slant submanifolds of the form $M_\theta \times_f M_\perp$; while M_θ is pointwise slant. For the survey on this topic we refer to Chen’s books [6, 9] and his survey article [7]. We also note that, in [21], we studied warped product bi-slant submanifolds of Kaehler manifolds which is a more general case of warped product submanifolds.

The paper is organised as follows: In Section 2 we give basic information needed for this paper. In Section 3, we define and studied pointwise hemi-slant submanifolds of Kaehler manifolds. In Section 4, we study warped product pointwise hemi-slant submanifolds of the form $M_\perp \times_f M_\theta$ in Kaehler manifolds such M_\perp is a totally real submanifold and M_θ is a pointwise submanifold. In this section, we provide an example and present a characterization theorem for such warped products.

2. Preliminaries

Let (\tilde{M}, J, g) be an almost Hermitian manifold with almost complex structure J and a Riemannian metric g such that

$$J^2 = -I, \tag{1}$$

$$g(JX, JY) = g(X, Y) \tag{2}$$

for all $X, Y \in \mathcal{X}(\tilde{M})$, where I is the identity map.

Let $\tilde{\nabla}$ denote the Levi-Civita connection on \tilde{M} . If the almost complex structure J satisfies

$$(\tilde{\nabla}_X J)Y = 0 \tag{3}$$

for $X, Y \in \mathcal{X}(\tilde{M})$, then \tilde{M} is called a *Kaehler manifold*.

Let M be a Riemannian manifold isometrically immersed in \tilde{M} . Then M is called a *complex* submanifold if $J(T_x M) \subseteq T_x M$ for any $x \in M$, where $T_x M$ is the tangent space of M at x . The submanifold M is called *totally real* if $J(T_x M) \subseteq T_x^\perp M$ for any $x \in M$, where $T_x^\perp M$ denotes the normal space of M at x .

Let M be a Riemannian manifold isometrically immersed in \tilde{M} and denote by the same symbol g the Riemannian metric induced on M . Let $\Gamma(TM)$ be the Lie algebra of vector fields in M and $\Gamma(T^\perp M)$, the set of all vector fields normal to M . Let ∇ be the Levi-Civita connection on M , then the Gauss and Weingarten formulas are respectively given by

$$\tilde{\nabla}_X Y = \nabla_X Y + h(X, Y) \tag{4}$$

and

$$\widetilde{\nabla}_X N = -A_N X + \nabla_X^\perp N \quad (5)$$

for any $X, Y \in \Gamma(TM)$ and $N \in \Gamma(T^\perp M)$, where ∇^\perp is the normal connection in the normal bundle $T^\perp M$ and A_N is the shape operator of M with respect to N . Moreover, $h : TM \times TM \rightarrow T^\perp M$ is the second fundamental form of M in \widetilde{M} . Furthermore, A_N and h are related by [22]

$$g(h(X, Y), N) = g(A_N X, Y) \quad (6)$$

for any $X, Y \in \Gamma(TM)$ and $N \in \Gamma(T^\perp M)$.

For any X tangent to M , we write

$$JX = PX + FX, \quad (7)$$

where PX and FX are the tangential and normal components of JX , respectively. Then P is an endomorphism of tangent bundle TM and ω is a normal bundle valued 1-form on TM . Similarly, for any vector field N normal to M , we put

$$JN = tN + fN, \quad (8)$$

where tN and fN are the tangential and normal components of JN , respectively. Moreover, from (2) and (7), we have $g(PX, Y) = -g(X, PY)$, for any $X, Y \in \Gamma(TM)$.

A submanifold M of a locally product Riemannian manifold \widetilde{M} is said to be *totally umbilical submanifold* if $h(X, Y) = g(X, Y)H$, for any $X, Y \in \Gamma(TM)$, where $H = \frac{1}{n} \sum_{i=1}^n h(e_i, e_i)$, the mean curvature vector of M . A submanifold M is said to be *totally geodesic* if $h(X, Y) = 0$. A totally umbilical submanifold of dimension greater than or equal to 2 with non-vanishing parallel mean curvature vector is called an *extrinsic sphere*.

A (differentiable) distribution \mathcal{D} defined on a submanifold M of (\widetilde{M}, J, g) is called *pointwise θ -slant* if, for each point $p \in M$, the Wirtinger angle $\theta(X)$ between JX and \mathcal{D} is independent of the choice of the nonzero vector $X \in \mathcal{D}$ (cf. [2, 3, 8]). A pointwise θ -slant distribution is called *slant* if θ is globally constant. Also, it is holomorphic or complex if $\theta = 0$; and it is called *totally real* if $\theta = \frac{\pi}{2}$, globally. A pointwise θ -slant distribution is called *proper pointwise slant* whenever $\theta \neq 0, \frac{\pi}{2}$ and θ is not a constant.

From Chen's result (Lemma 2.1) of [8], it is known that M is a pointwise slant submanifold of an almost Hermitian manifold \widetilde{M} if and only if

$$P^2 = -(\cos^2 \theta)I, \quad (9)$$

for some real-valued function θ defined on M , where I denotes the identity transformation of the tangent bundle TM of M . The following relations are the consequences of (9) as

$$g(PX, PY) = \cos^2 \theta g(X, Y), \quad (10)$$

$$g(FX, FY) = \sin^2 \theta g(X, Y) \quad (11)$$

for any $X, Y \in \Gamma(TM)$. Another important relation for a pointwise slant submanifold of an almost Hermitian manifold is obtained by using (1), (7), (8) and (9) as

$$tFX = -(\sin^2 \theta)X, \quad fFX = -FPX \quad (12)$$

for any $X \in \Gamma(TM)$.

3. Pointwise Hemi-slant Submanifolds

In this section, we study pointwise hemi-slant submanifolds of Kaehler manifolds. First, we define these submanifolds as follows.

Definition 3.1. Let \tilde{M} be a Kaehler manifold and M a real submanifold of \tilde{M} . Then, we say that M is a pointwise hemi-slant submanifold if there exists a pair of orthogonal distributions \mathcal{D}^\perp and \mathcal{D}^θ on M such that

- (i) The tangent space TM admits the orthogonal direct decomposition $TM = \mathcal{D}^\perp \oplus \mathcal{D}^\theta$.
- (ii) The distribution \mathcal{D}^\perp is totally real, i.e. $J(\mathcal{D}^\perp) \subset T^\perp M$.
- (iii) The distribution \mathcal{D}^θ is pointwise slant with slant function θ .

In the above definition, the angle θ is called the slant function of the pointwise slant distribution \mathcal{D}^θ . The totally real distribution \mathcal{D}^\perp of a pointwise hemi-slant submanifold is a pointwise slant distribution with slant function $\theta = \frac{\pi}{2}$. If we denote the dimensions of \mathcal{D}^\perp and \mathcal{D}^θ by m_1 and m_2 , respectively, then we have the following possible cases:

- (i) If $m_1 = 0$, then M is a pointwise slant submanifold.
- (ii) If $m_2 = 0$, then M is a totally real submanifold.
- (iii) If $m_1 = 0$ and $\theta = 0$, then M is a holomorphic submanifold.
- (iv) If θ is constant on M , then M is a hemi-slant submanifold with slant angle θ .
- (v) If $\theta = 0$, then M is a CR-submanifold.

We note that a pointwise hemi-slant submanifold is proper if $m_1 \neq 0$ and θ is not a constant. The normal bundle $T^\perp M$ of a pointwise hemi-slant submanifold M is decomposed by

$$T^\perp M = \varphi \mathcal{D}^\perp \oplus F\mathcal{D}^\theta, \quad \varphi \mathcal{D}^\perp \perp F\mathcal{D}^\theta.$$

Now, we give the following useful lemma.

Lemma 3.2. Let M be a pointwise hemi-slant submanifold of a Kaehler manifold \tilde{M} . Then the totally real distribution \mathcal{D}^\perp is always integrable.

The proof of Lemma 3.2 is similar to Theorem 3.5 of [16].

Lemma 3.3. Let M be a pointwise hemi-slant submanifold of a Kaehler manifold \tilde{M} . Then

- (i) For any $X, Y \in \Gamma(\mathcal{D}^\theta)$ and $Z \in \Gamma(\mathcal{D}^\perp)$, we have

$$\cos^2 \theta g(\nabla_X Y, Z) = g(A_{JZ}PY, X) - g(A_{FPY}Z, X). \tag{13}$$

- (ii) For any $Z, V \in \Gamma(\mathcal{D}^\perp)$ and $X \in \Gamma(\mathcal{D}^\theta)$, we have

$$\cos^2 \theta g(\nabla_Z V, X) = g(A_{FPX}V, Z) - g(A_{JV}PX, Z). \tag{14}$$

Proof. We prove (i) and (ii) in a similar way. For any $X, Y \in \Gamma(\mathcal{D}^\theta)$ and $Z \in \Gamma(\mathcal{D}^\perp)$, we have

$$g(\nabla_X Y, Z) = g(\tilde{\nabla}_X Y, Z) = g(J\tilde{\nabla}_X Y, JZ).$$

Using (3) and (7), we obtain

$$\begin{aligned} g(\nabla_X Y, Z) &= g(\tilde{\nabla}_X PY, JZ) + g(\tilde{\nabla}_X FY, JZ) \\ &= g(h(X, PY), JZ) - g(\tilde{\nabla}_X JFY, Z). \end{aligned}$$

Then from (8), we get

$$g(\nabla_X Y, Z) = g(h(A_{JZ}PY, X) - g(\tilde{\nabla}_X tFY, Z) - g(\tilde{\nabla}_X fFY, Z).$$

Thus from (12), we derive

$$\begin{aligned} g(\nabla_X Y, Z) &= g(h(A_{JZ}PY, X) + g(\widetilde{\nabla}_X \sin^2 \theta Y, Z) + g(\widetilde{\nabla}_X FPY, Z)). \\ &= g(h(A_{FZ}PY, X) + \sin^2 \theta g(\widetilde{\nabla}_X Y, Z) + \sin 2\theta X(\theta) g(Y, Z) \\ &\quad - g(A_{FPY}X, Z)). \end{aligned}$$

Then by the orthogonality of two distributions and the symmetry of the shape operator, we get (i). In a similar way we can prove (ii). \square

4. Warped Products $M_{\perp} \times_f M_{\theta}$ in Kaehler Manifolds

In [1], Bishop and O’Neill introduced the notion of warped product manifolds as follows: Let M_1 and M_2 be two Riemannian manifolds with Riemannian metrics g_1 and g_2 , respectively, and a positive differentiable function f on M_1 . Consider the product manifold $M_1 \times M_2$ with its projections $\pi_1 : M_1 \times M_2 \rightarrow M_1$ and $\pi_2 : M_1 \times M_2 \rightarrow M_2$. Then their warped product manifold $M = M_1 \times_f M_2$ is the Riemannian manifold $M_1 \times M_2 = (M_1 \times M_2, g)$ equipped with the Riemannian structure such that

$$g(X, Y) = g_1(\pi_{1\star}X, \pi_{1\star}Y) + (f \circ \pi_1)^2 g_2(\pi_{2\star}X, \pi_{2\star}Y)$$

for any vector field X, Y tangent to M , where \star is the symbol for the tangent maps. A warped product manifold $M = M_1 \times_f M_2$ is said to be *trivial* or simply a *Riemannian product manifold* if the warping function f is constant. Let X be an unit vector field tangent to M_1 and Z be an another unit vector field on M_2 , then from Lemma 7.3 of [1], we have

$$\nabla_X Z = \nabla_Z X = X(\ln f)Z \tag{15}$$

where ∇ is the Levi-Civita connection on M . If $M = M_1 \times_f M_2$ be a warped product manifold then the base manifold M_1 is totally geodesic in M and the fiber M_2 is totally umbilical in M [1, 4].

Analogous to CR-warped products introduced in [4], we define the notion of warped product pointwise hemi-slant submanifolds as follows.

Definition 4.1. A warped product $M_{\perp} \times_f M_{\theta}$ of totally real and pointwise slant submanifolds M_{\perp} and M_{θ} of an almost Hermitian manifold (\widetilde{M}, J, g) is called a *warped product pointwise hemi-slant submanifold*.

A warped product pointwise hemi-slant submanifold $M_{\perp} \times_f M_{\theta}$ is called *proper* if M_{θ} is proper pointwise slant and M_{\perp} is totally real in \widetilde{M} . Otherwise, $M_{\perp} \times_f M_{\theta}$ is called *non-proper*.

In [16], Sahin proved that there are no warped product hemi-slant submanifolds of the form $M_{\perp} \times_f M_{\theta}$ in a Kaehler manifold \widetilde{M} such that M_{θ} is proper slant. But if we assume that M_{θ} is a pointwise slant submanifold of \widetilde{M} , then there exists a class of nontrivial warped products.

Next, we provide an example of warped product pointwise hemi-slant submanifold of the form $M_{\perp} \times_f M_{\theta}$ such M_{θ} is a pointwise slant submanifold.

Let \mathbb{E}^{2n} be the Euclidean $2n$ -space with the standard metric and let \mathbb{C}^n denote the complex Euclidean n -space (\mathbb{E}^{2n}, J) equipped with the canonical complex structure J defined by

$$J(x_1, y_1, \dots, x_n, y_n) = (-y_1, x_1, \dots, -y_n, x_n).$$

Thus we have

$$J\left(\frac{\partial}{\partial x_i}\right) = -\frac{\partial}{\partial y_i}, \quad J\left(\frac{\partial}{\partial y_i}\right) = \frac{\partial}{\partial x_i}, \quad i = 1, \dots, n. \tag{16}$$

Example 4.2. Consider a submanifold M of \mathbb{R}^{10} defined by

$$\phi(u, v, w) = (u \cos v, u \sin v, u \cos w, u \sin w, -v + w, v + w, -u \cos v, u \sin v, -u \cos w, u \sin w).$$

such that $u \neq 0$ is a real valued function on M . It is easy to see that the tangent bundle TM of M is spanned by the following vectors

$$\begin{aligned} Z_1 &= \cos v \frac{\partial}{\partial x_1} + \sin v \frac{\partial}{\partial y_1} + \cos w \frac{\partial}{\partial x_2} + \sin w \frac{\partial}{\partial y_2} - \cos v \frac{\partial}{\partial x_4} \\ &\quad + \sin v \frac{\partial}{\partial y_4} - \cos w \frac{\partial}{\partial x_5} + \sin w \frac{\partial}{\partial y_5}, \\ Z_2 &= -u \sin v \frac{\partial}{\partial x_1} + u \cos v \frac{\partial}{\partial y_1} - \frac{\partial}{\partial x_3} + \frac{\partial}{\partial y_3} + u \sin v \frac{\partial}{\partial x_4} + u \cos v \frac{\partial}{\partial y_4}, \\ Z_3 &= -u \sin w \frac{\partial}{\partial x_2} + u \cos w \frac{\partial}{\partial y_2} + \frac{\partial}{\partial x_3} + \frac{\partial}{\partial y_3} + u \sin w \frac{\partial}{\partial x_5} + u \cos w \frac{\partial}{\partial y_5}. \end{aligned}$$

Then, using the canonical complex structure (16) of \mathbb{R}^{10} , we have

$$\begin{aligned} JZ_1 &= -\cos v \frac{\partial}{\partial y_1} + \sin v \frac{\partial}{\partial x_1} - \cos w \frac{\partial}{\partial y_2} + \sin w \frac{\partial}{\partial x_2} + \cos v \frac{\partial}{\partial y_4} \\ &\quad + \sin v \frac{\partial}{\partial x_4} + \cos w \frac{\partial}{\partial y_5} + \sin w \frac{\partial}{\partial x_5}, \\ JZ_2 &= u \sin v \frac{\partial}{\partial y_1} + u \cos v \frac{\partial}{\partial x_1} + \frac{\partial}{\partial y_3} + \frac{\partial}{\partial x_3} - u \sin v \frac{\partial}{\partial y_4} + u \cos v \frac{\partial}{\partial x_4}, \\ JZ_3 &= u \sin w \frac{\partial}{\partial y_2} + u \cos w \frac{\partial}{\partial x_2} - \frac{\partial}{\partial y_3} + \frac{\partial}{\partial x_3} - u \sin w \frac{\partial}{\partial y_5} + u \cos w \frac{\partial}{\partial x_5}. \end{aligned}$$

It is clear that JZ_1 is orthogonal to TM . Thus $\mathcal{D}^\perp = \text{Span}\{Z_1\}$ is a totally real distribution. Moreover, it is easy to see that $\mathcal{D}^\theta = \text{Span}\{Z_2, Z_3\}$ is a pointwise slant distribution with slant function $\theta = \cos^{-1}\left(\frac{1}{1+u^2}\right)$. It is easy to verify that both distributions \mathcal{D}^\perp and \mathcal{D}^θ are completely integrable. Let M_\perp and M_θ be the integral manifolds of \mathcal{D}^\perp and \mathcal{D}^θ , respectively. Then the metric tensor of M is given by

$$g = 4du^2 + (2 + 2u^2)(dv^2 + dw^2) = g_{M_\perp} + \left(\sqrt{2(1 + u^2)}\right)^2 g_{M_\theta},$$

where g_{M_θ} and g_{M_\perp} are the metric tensors of M_θ and M_\perp , respectively. Consequently, $M = M_\perp \times_f M_\theta$ is a warped product pointwise hemi-slant submanifold of \mathbb{R}^{10} with warping function $f = \sqrt{2(1 + u^2)}$ and the slant function $\theta = \cos^{-1}\left(\frac{1}{1+u^2}\right)$.

Now, we investigate the geometry of the warped product pointwise hemi-slant submanifolds of form $M_\perp \times_f M_\theta$. First, we prove the following useful lemma for later use.

Lemma 4.3. Let $M = M_\perp \times_f M_\theta$ be a warped product pointwise hemi-slant submanifold of a Kaehler manifold \tilde{M} . Then

- (i) $g(h(Z, V), FX) = g(h(X, Z), JV)$;
- (ii) $g(h(X, Y), JZ) = Z(\ln f) g(X, PY) + g(h(X, Z), FY)$

for any $Z, V \in \Gamma(TM_{\perp})$ and $X, Y \in \Gamma(TM_{\theta})$.

Proof. For any $Z, V \in \Gamma(TM_{\perp})$ and $X \in \Gamma(TM_{\theta})$, we have

$$\begin{aligned} g(h(Z, V), FX) &= g(\widetilde{\nabla}_Z V, FX) \\ &= g(\widetilde{\nabla}_Z V, JX) - g(\widetilde{\nabla}_Z V, PX) \\ &= -g(\widetilde{\nabla}_Z JV, X) - g(\widetilde{\nabla}_Z PX, V). \end{aligned}$$

Then from (4), (5) and (15), we obtain

$$g(h(Z, V), FX) = g(A_{JV}Z, X) + Z(\ln f) g(PX, V).$$

From the orthogonality of the vector fields and (5), we find

$$g(h(Z, V), FX) = -g(h(X, Z), JV)$$

which is (i). For the second part of the lemma, we have

$$g(h(X, Y), JZ) = g(\widetilde{\nabla}_X Y, JZ) = -g(\widetilde{\nabla}_X JY, Z)$$

for any $X, Y \in \Gamma(TM_{\theta})$ and $Z \in \Gamma(TM_{\perp})$. Using (7) and (5), we obtain

$$\begin{aligned} g(h(X, Y), JZ) &= -g(\widetilde{\nabla}_X PY, Z) - g(\widetilde{\nabla}_X FY, Z) \\ &= g(\widetilde{\nabla}_X Z, PY) + g(A_{FY}X, Z). \end{aligned}$$

Thus, (ii) follows from the above relation by using (6) and (15), which proves the lemma completely. \square

If we interchange X by PX and Y by PY in Lemma 4.3 (ii), for any $X, Y \in \Gamma(TM_{\theta})$, then by using (9) and (10), we have the following relations

$$g(h(PX, Y), JZ) = \cos^2 \theta Z(\ln f) g(X, Y) + g(h(PX, Z), FY), \tag{17}$$

$$g(h(X, PY), JZ) = -\cos^2 \theta Z(\ln f) g(X, Y) + g(h(X, Z), FPY) \tag{18}$$

and

$$g(h(PX, PY), JZ) = \cos^2 \theta Z(\ln f) g(X, PY) + g(h(PX, Z), FPY). \tag{19}$$

Lemma 4.4. Let $M = M_{\perp} \times_f M_{\theta}$ be a proper warped product pointwise hemi-slant submanifold of a Kaehler manifold \widetilde{M} . Then

$$g(A_{FPX}Y - A_{FY}PX, Z) = 2 \cos^2 \theta Z(\ln f) g(X, Y)$$

for any $Z \in \Gamma(TM_{\perp})$ and $X, Y \in \Gamma(TM_{\theta})$.

Proof. Interchanging X by Y in Lemma 4.3 (ii), we have

$$\begin{aligned} g(h(X, Y), JZ) &= Z(\ln f) g(Y, PX) + g(h(Y, Z), FX) \\ &= -Z(\ln f) g(X, PY) + g(h(Y, Z), FX) \end{aligned} \tag{20}$$

Subtracting (20) from Lemma 4.3 (ii), thus we derive

$$g(h(Y, Z), FX) - g(h(X, Z), FY) = 2Z(\ln f) g(X, PY). \tag{21}$$

Interchange X by PX in (21) and using (10), we obtain

$$2 \cos^2 \theta Z(\ln f) g(X, Y) = g(h(Y, Z), FPX) - g(h(PX, Z), FY). \tag{22}$$

Hence, the result follows from (22) by using (6). \square

A warped product manifold $M = M_1 \times_f M_2$ is said to be *mixed totally geodesic* if $h(X, Z) = 0$, for any $X \in \Gamma(TM_1)$ and $Z \in \Gamma(TM_2)$.

The following corollary is an immediate consequence of the above lemma.

Corollary 4.5. *There does not exist any proper warped product mixed totally geodesic submanifold of the form $M = M_\perp \times_f M_\theta$ of a Kaehler manifold \tilde{M} such that M_\perp is a totally real submanifold and M_θ is a proper pointwise slant submanifold of \tilde{M} .*

Proof. The proof of the corollary follows from (22) by using the mixed totally geodesic condition. \square

We note that the above corollary is also given in [18] as a remark.

Lemma 4.6. *Let $M = M_\perp \times_f M_\theta$ be a proper warped product pointwise hemi-slant submanifold of a Kaehler manifold \tilde{M} . Then*

$$g(h(X, Z), FY) - g(h(Y, Z), FX) = 2 \tan \theta Z(\theta) g(PX, Y) \quad (23)$$

for any $Z \in \Gamma(TM_\perp)$ and $X, Y \in \Gamma(TM_\theta)$.

Proof. For any $X, Y \in \Gamma(TM_\theta)$ and $Z \in \Gamma(TM_\perp)$, we have

$$g(\tilde{\nabla}_Z X, Y) = g\nabla_Z X, Y = Z(\ln f) g(X, Y). \quad (24)$$

On the other hand, for any $X, Y \in \Gamma(TM_\theta)$ and $Z \in \Gamma(TM_\perp)$, we also have

$$g(\tilde{\nabla}_Z X, Y) = g(J\tilde{\nabla}_Z X, JY) = g(\tilde{\nabla}_Z JX, JY).$$

Using (2), (4), (7) and (15), we get

$$\begin{aligned} g(\tilde{\nabla}_Z X, Y) &= g(\tilde{\nabla}_Z PX, PY) + g(\tilde{\nabla}_Z PX, FY) + g(\tilde{\nabla}_Z FX, JY) \\ &= \cos^2 \theta Z(\ln f) g(X, Y) + g(h(Z, PX), FY) - g(\tilde{\nabla}_Z JFX, Y). \end{aligned}$$

Then from (8), we derive

$$\begin{aligned} g(\tilde{\nabla}_Z X, Y) &= \cos^2 \theta Z(\ln f) g(X, Y) + g(h(Z, PX), FY) - g(\tilde{\nabla}_Z JFX, Y) \\ &\quad - g(\tilde{\nabla}_Z JFX, Y). \end{aligned}$$

Using (12), we obtain

$$\begin{aligned} g(\tilde{\nabla}_Z X, Y) &= \cos^2 \theta Z(\ln f) g(X, Y) + g(h(Z, PX), FY) - g(\tilde{\nabla}_Z \sin^2 \theta X, Y) \\ &\quad + g(\tilde{\nabla}_Z FPX, Y) \\ &= \cos^2 \theta Z(\ln f) g(X, Y) + g(h(Z, PX), FY) + \sin^2 \theta g(\tilde{\nabla}_Z X, Y) \\ &\quad + \sin 2\theta Z(\theta) g(X, Y) - g(A_{FPX} Z, Y), \end{aligned}$$

which on using (6), the above equation takes the form

$$\begin{aligned} \cos^2 \theta g(\tilde{\nabla}_Z X, Y) &= \cos^2 \theta Z(\ln f) g(X, Y) + g(h(Z, PX), FY) \\ &\quad + \sin 2\theta Z(\theta) g(X, Y) - g(h(Y, Z), FPX). \end{aligned} \quad (25)$$

From (24) and (25), we derive

$$g(h(Y, Z), FPX) - g(h(Z, PX), FY) = \sin 2\theta Z(\theta) g(X, Y). \quad (26)$$

Interchanging X by PX in (26) and then using (9), we get the desired result. Hence, the proof is complete. \square

Now, we have the following useful theorem.

Theorem 4.7. *Let $M = M_{\perp} \times_f M_{\theta}$ be a warped product pointwise hemi-slant submanifold of a Kaehler manifold \widetilde{M} such that M_{\perp} is a totally real submanifold and M_{θ} is a pointwise slant submanifold with slant function θ of \widetilde{M} . Then*

$$Z(\ln f) = \tan \theta Z(\theta)$$

for any $Z \in \Gamma(TM_{\perp})$.

Proof. From (21) and (23), we have

$$(\tan \theta Z(\theta) - Z(\ln f)) g(PX, Y) = 0. \quad (27)$$

Interchanging Y by PY in (27) and using (10), we obtain

$$\cos^2 \theta (\tan \theta Z(\theta) - Z(\ln f)) g(X, Y) = 0. \quad (28)$$

Since M is proper, therefore $\cos^2 \theta \neq 0$, thus the proof follows from (28). \square

As an application, we have the following consequences of the above theorem.

1. If we assume $\theta = 0$ in Theorem 4.7, then the warped product is of the form $M = M_{\perp} \times_f M_T$, where M_T and M_{\perp} are holomorphic and totally real submanifolds of a Kaehler manifold \widetilde{M} , respectively. Thus, the Theorem 3.1 of [4] is a special case of Theorem 4.7 as follows.

Corollary 4.8. *(Theorem 3.1 [4]). If $M = M_{\perp} \times_f M_T$ be a warped product CR-submanifold of a Kaehler manifold \widetilde{M} such that M_{\perp} is a totally real submanifold and M_T is a holomorphic submanifold of \widetilde{M} , then M is a CR-product.*

2. Also, if we assume that the slant function θ is a constant, i.e., M_{θ} is a proper slant submanifold, then the warped product $M = M_{\perp} \times_f M_{\theta}$ is a hemi-slant warped product submanifold of a Kaehler manifold \widetilde{M} , where M_{\perp} and M_{θ} are totally real and proper slant submanifolds of \widetilde{M} , respectively. Then, Theorem 4.2 of [16] is a special case of Theorem 4.7 as follows.

Corollary 4.9. *(Theorem 4.2 [16]). Let \widetilde{M} be a Kaehler manifold. Then there exist no warped product submanifolds $M = M_{\perp} \times_f M_{\theta}$ of \widetilde{M} such that M_{\perp} is a totally real submanifold and M_{θ} is a proper slant submanifold of \widetilde{M} .*

In order to give another characterization we need the following well known result of S. Hiepko [12].

Hiepko's Theorem. *Let \mathcal{D}_1 and \mathcal{D}_2 be two orthogonal distribution on a Riemannian manifold M . Suppose that \mathcal{D}_1 and \mathcal{D}_2 both are involutive such that \mathcal{D}_1 is a totally geodesic foliation and \mathcal{D}_2 is a spherical foliation. Then M is locally isometric to a non-trivial warped product $M_1 \times_f M_2$, where M_1 and M_2 are integral manifolds of \mathcal{D}_1 and \mathcal{D}_2 , respectively.*

The following result gives a characterization of warped product pointwise hemi-slant submanifolds.

Theorem 4.10. [18] *Let M be a pointwise hemi-slant submanifold of a Kaehler manifold \widetilde{M} . Then M is locally a warped product submanifold of the form $M_{\perp} \times_f M_{\theta}$ if and only if*

$$A_{FPX}V - A_{JV}PX = V(\mu)(\cos^2 \theta)X, \quad \forall X \in \Gamma(\mathcal{D}^{\theta}), V \in \Gamma(\mathcal{D}^{\perp}) \quad (29)$$

for some smooth function μ on M satisfying $Y(\mu) = 0$, for any $Y \in \Gamma(\mathcal{D}^{\theta})$.

Remark 4.11. *The inequality for second fundamental form of these kind of warped products may not be evaluated. The reason is that: To evaluate the squared norm of the second fundamental form $\|h\|^2$ from Lemma 4.3 and the relations (17)–(19), we have to assume that either M is mixed totally geodesic or to discuss the equality case M must be a mixed totally geodesic warped product and in both cases M is mixed totally geodesic, but in case of mixed totally geodesic, these warped products do not exist (Corollary 4.5).*

Remark 4.12. *Theorem 4.10 is valid only for the pointwise slant fiber. For example, if θ is constant i.e., M_θ is proper slant, then this is the case of non-existence of warped products (see Theorem 4.2 of [16]) and if $\theta = 0$, i.e., the fiber is a holomorphic submanifold, then again from Theorem 3.1 of [4], this is a case of non-existence of warped products.*

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