



A Serrin Type Criterion for Incompressible Hydrodynamic Flow of Liquid Crystals in Dimension Three

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Abstract. In the paper, we establish a Serrin type criterion for strong solutions to a simplified density-dependent Ericksen-Leslie system modeling incompressible, nematic liquid crystal materials in dimension three. The density may vanish in an open subset of Ω . As a byproduct, we establish the Serrin type criterion for heat flow of harmonic map whose gradients belong to $L_x^r L_t^s$, where $\frac{2}{s} + \frac{3}{r} \leq 1$, for $3 < r \leq \infty$.

1. Introduction

We consider the following incompressible hydrodynamic flow of nematic liquids crystals in a bounded domain $\Omega \subset \mathbb{R}^3$:

$$\rho_t + \nabla \cdot (\rho u) = 0, \tag{1}$$

$$\rho u_t + \rho u \cdot \nabla u + \nabla P = \gamma \Delta u - \lambda \nabla \cdot (\nabla d \otimes \nabla d), \tag{2}$$

$$\nabla \cdot u = 0, \tag{3}$$

$$d_t + u \cdot \nabla d = \theta(\Delta d + |\nabla d|^2 d), \tag{4}$$

where $\rho : \Omega \times (0, \infty) \rightarrow \mathbb{R}_+$ is the density of the fluid, $u : \Omega \times (0, \infty) \rightarrow \mathbb{R}^3$ is the fluid velocity field, $d : \Omega \times (0, \infty) \rightarrow S^2$ represents the macroscopic average of the nematic liquid crystal orientation field; P denotes the pressure of the fluid, $\nabla \cdot (= \text{div})$ denotes the divergence operator on \mathbb{R}^3 ; γ, λ and θ are positive constants.

(1)-(4) is a simplified version of Ericksen-Leslie system modeling incompressible, nematic liquid crystal materials. For more details about this model, readers could be referred for instance to [1, 7–10]. For dimension $N = 2$ and $\rho = \text{const.}$, Lin, Lin and Wang [9] have proved the global existence of Leray-Hopf type weak solutions to (1)-(4) on bounded domains in \mathbb{R}^2 (see [4] for $\Omega = \mathbb{R}^2$). Lin and Wang [12] have further proved that such weak solutions are unique. A further discussion for $N = 2$ has been done by Xu and Zhang [17], where global regularity and uniqueness of weak solution with small initial data was proved. For $N = 3$, Wen and Ding [16] have established the local existence and uniqueness of strong solutions to (1)-(4). whether global weak (or smooth) solutions exist for $N = 3$ is still unknown. Recently, Huang

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and Wang [5] obtained a Beale-Kato-Majda criterion for smooth solutions to (1)-(4) in \mathbb{R}^3 when $\rho = \text{const.}$, namely, if $0 < T_* < \infty$ is the first singular time, then the $L_t^1 L_x^\infty$ -norm of the vorticity $\nabla \times u$ or the $L_t^2 L_x^\infty$ -norm of ∇d must become infinity when $t \nearrow T_*$.

We would like to point out that the system (1)-(4) includes two important equations as special cases:

(i) When u is zero, (4) becomes the heat flow of harmonic map (see [11]).

(ii) When d is a constant vector field, (1)-(3) becomes the nonhomogeneous incompressible Navier-Stokes equations (see [13]).

In this paper, we shall establish a Serrin type criterion for strong solutions to the system (1)-(4), along with the following initial-boundary condition:

$$(\rho, u, d)\Big|_{t=0} = (\rho_0, u_0, d_0), \tag{5}$$

and

$$\left(u, \frac{\partial d}{\partial \nu}\right)\Big|_{\partial\Omega} = 0, \tag{6}$$

where ν is the unit outward normal vector of $\partial\Omega$.

To state the definition of strong solutions to the initial-boundary-value problem (1)-(6), we give some notations which will be used throughout the paper.

Denote $Q_T = \Omega \times [0, T]$, $\int f dx = \int_\Omega f dx$, $L^q := L^q(\Omega)$, $W^{k,p} := W^{k,p}(\Omega)$, $H^k := W^{k,2}(\Omega)$.

Definition 1.1. (Strong solution) For $T > 0$, (ρ, u, d) is called a strong solution to the incompressible nematic liquid crystal system (1)-(6) in $\Omega \times (0, T]$, if

$$\begin{aligned} \rho &\in C([0, T]; W^{1,r}), \quad \rho_t \in C([0, T]; L^r), \quad \text{for some } r > 3, \\ u &\in C([0, T]; H^2 \cap H_0^1) \cap L^2(0, T; H^3), \\ u_t &\in L^2(0, T; H_0^1), \quad \sqrt{\rho}u_t \in L^\infty(0, T; L^2), \quad |d| = 1, \quad \text{in } \overline{Q_T}, \\ d &\in C([0, T]; H^3) \cap L^2(0, T; H^4), \quad d_t \in C([0, T]; H^1) \cap L^2(0, T; H^2), \\ d_{tt} &\in L^2(0, T; L^2). \end{aligned}$$

and (ρ, u, d) satisfies (1)-(4) a.e. in $\Omega \times (0, T]$.

The constants γ, λ, θ play no roles in the analysis, we assume $\gamma = \lambda = \theta = 1$ henceforth.

The existence of local strong solutions could be obtained in the paper [16], which might be slightly modified. More precisely,

Theorem 1.2. Assume that $\inf \rho_0 \geq 0$, $\rho_0 \in W^{1,r}$, for some $r > 3$, $u_0 \in H^2 \cap H_0^1$, $\nabla d_0 \in H^2$ and $|d_0| = 1$ in $\overline{\Omega}$, in addition, the following compatibility conditions are valid

$$\Delta u_0 - \nabla P_0 - \nabla \cdot (\nabla d_0 \otimes \nabla d_0) = \sqrt{\rho_0}g \quad \text{and} \quad \nabla \cdot u_0 = 0, \quad \text{in } \Omega, \tag{7}$$

for some $(P_0, g) \in H^1 \times L^2$. Then there exist a positive time $T_0 > 0$ and a unique strong solution (ρ, u, d) of (1)-(6) in $\Omega \times (0, T_0]$.

The main result here is stated as follows:

Theorem 1.3. Let (ρ, u, d) be a strong solution to (1)-(6). If $0 < T_* < +\infty$ is the maximum time of existence of the strong solutions, then

$$\int_0^{T_*} (\|u\|_{L^r}^s + \|\nabla d\|_{L^r}^s) dt = \infty, \tag{8}$$

where $\frac{2}{s} + \frac{3}{r} \leq 1$, for $3 < r \leq \infty$.

Remark 1.4. If d is a constant vector field, then (8) is the well-known Serrin type criterion for incompressible Navier-Stokes equations, see [2, 14].

Remark 1.5. If ρ and u are zero, then (8) with $r = 3, s = \infty$ has been established by Wang [15] for the heat flow of harmonic map.

2. Proof of Theorem 1.3

Let $0 < T_* < \infty$ be the maximum time for the existence of strong solution (ρ, u, d) to (1)-(6). Namely, (ρ, u, d) is a strong solution to (1)-(6) in $\Omega \times (0, T]$ for any $0 < T < T_*$, but not a strong solution in $\Omega \times (0, T_*]$. Suppose that (8) were false, i.e.

$$M_0 := \int_0^{T_*} (\|u\|_{L^r}^s + \|\nabla d\|_{L^r}^s) dt < \infty. \tag{1}$$

The goal is to show that under the assumption (1), there is a bound $C > 0$ depending only on $M_0, \rho_0, u_0, d_0, \Omega$, and T_* such that

$$\sup_{0 \leq t < T_*} [\|\sqrt{\rho}u_t\|_{L^2} + \|\rho\|_{W^{1,r}} + \|u\|_{H^2} + \|d\|_{H^3}] \leq C. \tag{2}$$

With (2), we can then show without much difficulty that T_* is not the maximum time, which is the desired contradiction.

Throughout the rest of the paper, we denote by C a generic constant depending only on $\rho_0, u_0, d_0, T_*, M_0, \Omega$. We denote by

$$A \lesssim B$$

if there exists a generic constant C such that $A \leq CB$. For two 3×3 matrices $M = (M_{ij}), N = (N_{ij})$, denote the scalar product between M and N by

$$M : N = \sum_{i,j=1}^3 M_{ij}N_{ij}.$$

For $d : \Omega \rightarrow S^2$, denote by $\nabla d \otimes \nabla d$ as the 3×3 matrix given by

$$(\nabla d \otimes \nabla d)_{ij} = \langle \nabla_i d, \nabla_j d \rangle, \quad 1 \leq i, j \leq 3.$$

The proof is divided into several steps, and we proceed as follows.

Step 1. We shall first establish upper-lower bounds of ρ . More precisely, we have

Lemma 2.1. Let $0 < T_* < +\infty$ be the maximum time for the strong solution (ρ, u, d) to (1)-(6). If (7) and (1) hold, then for a.e. $(x, t) \in \Omega \times [0, T_*)$, we have

$$0 \leq \inf_{x \in \Omega} \rho_0 \leq \rho \leq \sup_{x \in \Omega} \rho_0. \tag{3}$$

Proof. The proof is quite classical by using the characteristic methods (see for instance [6]). □

Step 2. We next establish the global energy inequality for strong solutions, namely,

Lemma 2.2. Let $0 < T_* < +\infty$ be the maximum time for the strong solution (ρ, u, d) to (1)-(6). If (7) and (1) hold, then for a.e. $t \in [0, T_*)$, we have

$$\begin{aligned} & \frac{1}{2} \int_{\Omega} (\rho|u|^2 + |\nabla d|^2)(t) dx + \int_0^t \int_{\Omega} (|\nabla u|^2 + |\Delta d + |\nabla d|^2 d|^2) dx ds \\ & = \frac{1}{2} \int_{\Omega} (\rho_0|u_0|^2 + |\nabla d_0|^2) dx. \end{aligned} \tag{4}$$

Proof. Multiplying (2) and (4) by u and $\Delta d + |\nabla d|^2 d$, respectively, integrating by parts over $\Omega \times [0, t]$, and using $|d| = 1$, we can easily get (4). \square

Step 3. Estimates of $(\nabla u, \nabla^2 d)$ in $L_t^\infty L_x^2$.

Lemma 2.3. Let $0 < T_* < +\infty$ be the maximum time for the strong solution (ρ, u, d) to (1)-(6). If (7) and (1) hold, then for a.e. $t \in [0, T_*)$, we have

$$\int_{\Omega} (|\nabla u|^2 + |\nabla^2 d|^2)(t) dx + \int_0^t \int_{\Omega} (\rho |u_t|^2 + |\nabla^3 d|^2 + |\nabla d_t|^2) dx dt \leq C. \tag{5}$$

Proof. Multiplying (2) by u_t , and integrating by parts over Ω , we obtain

$$\frac{1}{2} \frac{d}{dt} \int |\nabla u|^2 dx + \int \rho |u_t|^2 dx = - \int \rho (u \cdot \nabla) u \cdot u_t dx - \int \nabla \cdot (\nabla d \otimes \nabla d) \cdot u_t dx = \sum_{i=1}^2 I_i. \tag{6}$$

For I_1 , by Cauchy inequality and (3), we have

$$I_1 \leq \frac{1}{4} \int \rho |u_t|^2 dx + C \int |u|^2 |\nabla u|^2 dx. \tag{7}$$

Using Hölder inequality and interpolation inequality, we have

$$\int |u|^2 |\nabla u|^2 dx \leq C \|u\|_{L^r}^2 \|\nabla u\|_{L^{\frac{2r}{r-2}}}^2, \tag{8}$$

and

$$\|\nabla u\|_{L^{\frac{2r}{r-2}}} \leq \|\nabla u\|_{L^2}^{1-\frac{3}{r}} \|\nabla u\|_{L^6}^{\frac{3}{r}} \leq C \|\nabla u\|_{L^2}^{1-\frac{3}{r}} \|\nabla u\|_{H^1}^{\frac{3}{r}}. \tag{9}$$

(8) and (9), together with Cauchy inequality, yield

$$\int |u|^2 |\nabla u|^2 dx \leq C \|u\|_{L^r}^2 \|\nabla u\|_{L^2}^{2(1-\frac{3}{r})} \|\nabla u\|_{H^1}^{\frac{6}{r}} \leq C_\epsilon (\|u\|_{L^r}^\epsilon + 1) \|\nabla u\|_{L^2}^2 + \epsilon \|\nabla u\|_{H^1}^2, \tag{10}$$

for any $\epsilon \in (0, 1)$, where $\frac{2}{s} + \frac{3}{r} \leq 1$, for $3 < r \leq \infty$, which implies $\frac{2r}{r-3} \leq s$. If $r = \infty$, then (10) is obvious.

Since

$$-\Delta u + \nabla P = -\rho u_t - \rho u \cdot \nabla u - \nabla \cdot (\nabla d \otimes \nabla d),$$

we apply the H^2 -estimate for the Stokes equations (see for instance [3]), together with the similar arguments as (10), we have

$$\begin{aligned} \|\nabla u\|_{H^1}^2 &\leq \|\rho u_t\|_{L^2}^2 + \|\rho u \cdot \nabla u\|_{L^2}^2 + \int |\nabla d|^2 |\nabla^2 d|^2 dx \\ &\leq \|\sqrt{\rho} u_t\|_{L^2}^2 + \|u \cdot \nabla u\|_{L^2}^2 + (\|\nabla d\|_{L^r}^\epsilon + 1) \|\nabla^2 d\|_{L^2}^2 + \|\nabla^2 d\|_{H^1}^2, \end{aligned} \tag{11}$$

where we have used (3). Substituting (11) into (10), and taking $\epsilon \in (0, 1)$ sufficiently small, we obtain

$$\begin{aligned} \int |u|^2 |\nabla u|^2 dx &\leq C_\epsilon (\|u\|_{L^r}^\epsilon + 1) \|\nabla u\|_{L^2}^2 + C_\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2 + C_\epsilon (\|\nabla d\|_{L^r}^\epsilon + 1) \|\nabla^2 d\|_{L^2}^2 \\ &\quad + C_\epsilon \|\nabla^2 d\|_{H^1}^2. \end{aligned} \tag{12}$$

Substituting (12) into (7), we have

$$\begin{aligned} I_1 &\leq \frac{1}{4} \int \rho |u_t|^2 dx + C_\epsilon (\|u\|_{L^r}^\epsilon + 1) \|\nabla u\|_{L^2}^2 + C_\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2 \\ &\quad + C_\epsilon (\|\nabla d\|_{L^r}^\epsilon + 1) \|\nabla^2 d\|_{L^2}^2 + C_\epsilon \|\nabla^2 d\|_{H^1}^2. \end{aligned} \tag{13}$$

For I_2 , using Cauchy inequality, we have

$$\begin{aligned}
 I_2 &= \int \nabla d \otimes \nabla d : \nabla u_t \, dx \\
 &= \frac{d}{dt} \int \nabla d \otimes \nabla d : \nabla u \, dx - \int \nabla d_t \otimes \nabla d : \nabla u \, dx - \int \nabla d \otimes \nabla d_t : \nabla u \, dx \\
 &\leq \frac{d}{dt} \int \nabla d \otimes \nabla d : \nabla u \, dx + C_\epsilon \int |\nabla d|^2 |\nabla u|^2 \, dx + \epsilon \|\nabla d_t\|_{L^2}^2.
 \end{aligned}
 \tag{14}$$

To estimate the second term of the right hand side of (14), we apply the similar arguments as (10). Then

$$\int |\nabla d|^2 |\nabla u|^2 \, dx \leq C_\epsilon (\|\nabla d\|_{L^r}^s + 1) \|\nabla u\|_{L^2}^2 + \epsilon \|\nabla u\|_{H^1}^2.
 \tag{15}$$

Substituting (11) and (12) into (15), we obtain

$$\begin{aligned}
 \int |\nabla d|^2 |\nabla u|^2 \, dx &\leq C_\epsilon (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) \|\nabla u\|_{L^2}^2 + C\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2 \\
 &\quad + C_\epsilon (\|\nabla d\|_{L^r}^s + 1) \|\nabla^2 d\|_{L^2}^2 + C\epsilon \|\nabla^2 d\|_{H^1}^2.
 \end{aligned}
 \tag{16}$$

Putting (13), (14) and (16) into (6), choosing ϵ sufficiently small, we obtain

$$\begin{aligned}
 \frac{d}{dt} \int |\nabla u|^2 \, dx + \int \rho |u_t|^2 \, dx &\leq 2 \frac{d}{dt} \int \nabla d \otimes \nabla d : \nabla u \, dx + C_\epsilon (\|u\|_{L^r}^s + \|\nabla d\|_{L^r}^s + 1) \|\nabla u\|_{L^2}^2 \\
 &\quad + C_\epsilon (\|\nabla d\|_{L^r}^s + 1) \|\nabla^2 d\|_{L^2}^2 + C\epsilon \|\nabla^2 d\|_{H^1}^2 + C\epsilon \|\nabla d_t\|_{L^2}^2.
 \end{aligned}
 \tag{17}$$

Integrating (17) over $[0, t]$, for $0 < t < T_*$, and applying Cauchy inequality, we obtain

$$\begin{aligned}
 &\int |\nabla u|^2 \, dx + \int_0^t \int \rho |u_t|^2 \, dx \, ds \\
 &\leq \frac{1}{2} \|\nabla u\|_{L^2}^2 + C \int |\nabla d|^4 \, dx + C_\epsilon \int_0^t (\|u\|_{L^r}^s + \|\nabla d\|_{L^r}^s + 1) \|\nabla u\|_{L^2}^2 \, ds \\
 &\quad + C_\epsilon \int_0^t (\|\nabla d\|_{L^r}^s + 1) \|\nabla^2 d\|_{L^2}^2 \, ds + C\epsilon \int_0^t \|\nabla^2 d\|_{H^1}^2 \, ds + C\epsilon \int_0^t \|\nabla d_t\|_{L^2}^2 \, ds + C.
 \end{aligned}$$

Thus,

$$\begin{aligned}
 &\int |\nabla u|^2 \, dx + \int_0^t \int \rho |u_t|^2 \, dx \, ds \\
 &\leq C \int |\nabla d|^4 \, dx + C_\epsilon \int_0^t (\|u\|_{L^r}^s + \|\nabla d\|_{L^r}^s + 1) \|\nabla u\|_{L^2}^2 \, ds \\
 &\quad + C_\epsilon \int_0^t (\|\nabla d\|_{L^r}^s + 1) \|\nabla^2 d\|_{L^2}^2 \, ds + C\epsilon \int_0^t \|\nabla^2 d\|_{H^1}^2 \, ds + C\epsilon \int_0^t \|\nabla d_t\|_{L^2}^2 \, ds + C.
 \end{aligned}
 \tag{18}$$

Next, we shall make some estimates about d . To do these, differentiating (4) with respect to x , we have

$$\nabla d_t - \nabla \Delta d = -\nabla(u \cdot \nabla d) + \nabla(|\nabla d|^2 d).
 \tag{19}$$

Multiplying (19) by $4|\nabla d|^2 \nabla d$, and integrating by parts over Ω , we have

$$\begin{aligned}
 &\frac{d}{dt} \int |\nabla d|^4 \, dx + 4 \int (|\nabla d|^2 |\nabla^2 d|^2 + 2|\nabla d|^2 |\nabla |\nabla d||^2) \, dx \\
 &= 4 \int \nabla(|\nabla d|^2 d) |\nabla d|^2 \nabla d \, dx - 4 \int \nabla(u \cdot \nabla d) |\nabla d|^2 \nabla d \, dx = \sum_{i=1}^2 II_i.
 \end{aligned}
 \tag{20}$$

Since

$$\nabla(|\nabla d|^2 d) = |\nabla d|^2 \nabla d + \nabla(|\nabla d|^2) d \text{ and } \nabla d \cdot d = 0,$$

for I_1 , we have

$$I_1 = 4 \int |\nabla d|^6 dx \lesssim \int |\nabla d|^2 |\Delta d|^2 dx, \tag{21}$$

where we have used the fact

$$|d| = 1, \text{ and } |\nabla d|^2 = -\Delta d \cdot d \leq |\Delta d|. \tag{22}$$

Using the similar arguments as (10), we have

$$\int |\nabla d|^2 |\Delta d|^2 dx \leq C_\epsilon (\|\nabla d\|_{L^r}^s + 1) \|\Delta d\|_{L^2}^2 + \epsilon \|\Delta d\|_{H^1}^2. \tag{23}$$

Thus,

$$I_1 \leq C_\epsilon (\|\nabla d\|_{L^r}^s + 1) \|\Delta d\|_{L^2}^2 + \epsilon \|\Delta d\|_{H^1}^2. \tag{24}$$

For I_2 , using (22) again, together with integration by parts, $\operatorname{div} u = 0$ and Cauchy inequality, we have

$$\begin{aligned} I_2 &\lesssim \int |\nabla d|^4 |\nabla u| dx - \int u \cdot \nabla(|\nabla d|^4) dx \\ &\lesssim \int |\nabla d|^2 |\Delta d| |\nabla u| dx \\ &\lesssim \int |\nabla d|^2 |\Delta d|^2 dx + \int |\nabla d|^2 |\nabla u|^2 dx. \end{aligned} \tag{25}$$

Putting (16), (23) into (25), and then substituting the resulting inequality and (24) into (20), we obtain

$$\begin{aligned} &\frac{d}{dt} \int |\nabla d|^4 dx + 4 \int (|\nabla d|^2 |\nabla^2 d|^2 + 2|\nabla d|^2 |\nabla |\nabla d|^2|) dx \\ &\leq C_\epsilon (\|\nabla d\|_{L^r}^s + 1) \|\nabla^2 d\|_{L^2}^2 + C_\epsilon \|\nabla^2 d\|_{H^1}^2 + C_\epsilon (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) \|\nabla u\|_{L^2}^2 \\ &\quad + C_\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2. \end{aligned} \tag{26}$$

Multiplying (19) by $\nabla \Delta d$, integrating by parts over Ω and using $\frac{\partial d_t}{\partial \nu} = 0$ on $\partial\Omega$, we obtain

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \int |\Delta d|^2 dx + \|\nabla \Delta d\|_{L^2}^2 = \int (\nabla(u \cdot \nabla d) - \nabla(|\nabla d|^2 d)) : \nabla \Delta d dx \\ &\leq \epsilon \|\Delta d\|_{H^1}^2 + C_\epsilon \int (|\nabla u|^2 |\nabla d|^2 + |u|^2 |\nabla^2 d|^2) dx + C_\epsilon \int |\nabla d|^2 |\nabla^2 d|^2 dx + C_\epsilon \int |\nabla d|^6 dx \\ &\leq \epsilon C \|\nabla \Delta d\|_{L^2}^2 + C_\epsilon (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) + C_\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2, \end{aligned}$$

where we have used (16), (21) and (23), together with the arguments as (10) dealing with the term $\int |u|^2 |\nabla^2 d|^2$ (replacing the second u on the left side of (10) by ∇d). Choosing ϵ sufficiently small, we have

$$\begin{aligned} &\frac{d}{dt} \int |\Delta d|^2 dx + \frac{3}{2} \|\nabla \Delta d\|_{L^2}^2 \\ &\leq C_\epsilon (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) + C_\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2. \end{aligned} \tag{27}$$

Multiplying (19) by ∇d_t , integrating by parts over Ω , and using $\frac{\partial d_t}{\partial \nu} = 0$ on $\partial\Omega$, we have

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \int |\Delta d|^2 dx + \|\nabla d_t\|_{L^2}^2 = \int (\nabla(|\nabla d|^2 d) - \nabla(u \cdot \nabla d)) \nabla d_t dx \\ &\leq \epsilon \|\nabla d_t\|_{L^2}^2 + C \int (|\nabla d|^2 |\nabla^2 d|^2 + |\nabla d|^6 + |\nabla u|^2 |\nabla d|^2 + |u|^2 |\nabla^2 d|^2) dx \\ &\leq \epsilon \|\nabla d_t\|_{L^2}^2 + \epsilon C \|\nabla \Delta d\|_{L^2}^2 + C_\epsilon (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) + C_\epsilon \|\sqrt{\rho} u_t\|_{L^2}^2. \end{aligned} \tag{28}$$

Putting (26), (27) and (28) together, choosing ϵ sufficiently small, we have

$$\begin{aligned} & \frac{d}{dt} \int (|\Delta d|^2 + |\nabla d|^4) dx + \int (|\nabla \Delta d|^2 + |\nabla d_t|^2 + |\nabla d|^2 |\nabla^2 d|^2) dx \\ & \leq (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) + C\epsilon \|\sqrt{\rho}u_t\|_{L^2}^2. \end{aligned} \tag{29}$$

Integrating (29) from 0 to t , for $0 < t < T_*$, and using the standard elliptic estimates for Neumann problem and (4), we obtain

$$\begin{aligned} & \int (|\nabla^2 d|^2 + |\nabla d|^4)(t) dx + \int_0^t \int (|\nabla^3 d|^2 + |\nabla d_t|^2 + |\nabla d|^2 |\nabla^2 d|^2) dx ds \\ & \leq C \int_0^t (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) ds + C\epsilon \int_0^t \|\sqrt{\rho}u_t\|_{L^2}^2 ds + C. \end{aligned} \tag{30}$$

Multiplying (30) by $2C$ and adding the resulting inequality into (18), choosing ϵ sufficiently small, we have

$$\begin{aligned} & \int (|\nabla u|^2 + |\nabla^2 d|^2)(t) dx + \int_0^t \int (\rho|u_t|^2 + |\nabla^3 d|^2 + |\nabla d_t|^2) dx ds \\ & \leq C \int_0^t (\|\nabla d\|_{L^r}^s + \|u\|_{L^r}^s + 1) (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) ds + C. \end{aligned} \tag{31}$$

By Gronwall inequality and (1), we get (5). □

As an immediate consequence of Lemma 2.3, we have

Corollary 2.4. *Let $0 < T_* < +\infty$ be the maximum time for the strong solution (ρ, u, d) to (1)-(6). If (7) and (1) hold, then for a.e. $t \in [0, T_*)$, we have*

$$\int_{\Omega} |d_t|^2(t) dx + \int_0^t \|\nabla u\|_{H^1}^2(s) ds \leq C. \tag{32}$$

Proof. It follows from (4) and (5) that

$$\int_{\Omega} |d_t|^2 \leq C.$$

By (11), (12), (1) and (5), we get the last part of (32). □

Step 4. Estimates of $(\nabla^2 u, \nabla^3 d)$ in $L_t^\infty L_x^2$.

Lemma 2.5. *Let $0 < T_* < +\infty$ be the maximum time for the strong solution (ρ, u, d) to (1)-(6). If (7) and (1) hold, then for a.e. $t \in [0, T_*)$, we have*

$$\|\sqrt{\rho}u_t\|_{L^2} + \|\nabla d_t\|_{L^2} + \|\nabla d\|_{H^2} + \int_0^t \int_{\Omega} (|\nabla u_t|^2 + |d_{tt}|^2) dx dt \leq C. \tag{33}$$

Proof. Differentiating the equation (2) with respect to t , we get

$$\begin{aligned} & \rho u_{tt} + \rho_t u_t + \rho u \cdot \nabla u_t + \rho_t u \cdot \nabla u + \rho u_t \cdot \nabla u + \nabla P_t \\ & = \Delta u_t - \nabla \cdot (\nabla d_t \otimes \nabla d + \nabla d \otimes \nabla d_t). \end{aligned} \tag{34}$$

Multiplying (34) by u_t , integrating by parts over Ω , and using (1), (3), Sobolev inequality, and Hölder inequality, we have

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int \rho |u_t|^2 dx + \int |\nabla u_t|^2 dx \\ & \leq \int (\rho |u| |\nabla u_t| |u_t| + \rho |u| |\nabla u|^2 |u_t| + \rho |u|^2 |\nabla^2 u| |u_t| + \rho |u|^2 |\nabla u| |\nabla u_t| \\ & \quad + \rho |u_t|^2 |\nabla u| + |\nabla d_t| |\nabla d| |\nabla u_t|) dx \\ & = \sum_{j=1}^6 III_j. \end{aligned} \tag{35}$$

For III_1 and III_5 , we have

$$\begin{aligned} III_1 + III_5 & \leq \|\sqrt{\rho}\|_{L^\infty} \|u\|_{L^6} \|\sqrt{\rho} u_t\|_{L^3} \|\nabla u_t\|_{L^2} + \|\sqrt{\rho}\|_{L^\infty} \|\nabla u\|_{L^2} \|\sqrt{\rho} u_t\|_{L^3} \|u_t\|_{L^6} \\ & \leq \|\sqrt{\rho} u_t\|_{L^2}^{\frac{1}{2}} \|\sqrt{\rho} u_t\|_{L^6}^{\frac{1}{2}} \|\nabla u_t\|_{L^2} \leq \|\sqrt{\rho} u_t\|_{L^2}^{\frac{1}{2}} \|\nabla u_t\|_{L^2}^{\frac{3}{2}} \\ & \leq \frac{1}{6} \|\nabla u_t\|_{L^2}^2 + C \|\sqrt{\rho} u_t\|_{L^2}^2, \end{aligned}$$

where we have used Hölder inequality, Sobolev inequality, (3), (5), the interpolation inequality and Young inequality.

Similarly, we have

$$\begin{aligned} III_2 + III_3 + III_4 & \leq \|\rho\|_{L^\infty} \|u\|_{L^6} \|u_t\|_{L^6} \|\nabla u\|_{L^3}^2 + \|\rho\|_{L^\infty} \|u\|_{L^6}^2 \|\nabla^2 u\|_{L^2} \|u_t\|_{L^6} \\ & \quad + \|\rho\|_{L^\infty} \|u\|_{L^6}^2 \|\nabla u\|_{L^6} \|\nabla u_t\|_{L^2} \\ & \leq \|\nabla u_t\|_{L^2} \|\nabla u\|_{L^2} \|\nabla u\|_{H^1} + \|\nabla u\|_{H^1} \|\nabla u_t\|_{L^2} \leq \frac{1}{6} \|\nabla u_t\|_{L^2}^2 + C \|\nabla u\|_{H^1}^2, \end{aligned}$$

and

$$III_6 \leq \|\nabla u_t\|_{L^2} \|\nabla d_t\|_{L^3} \|\nabla d\|_{L^6} \leq \frac{1}{6} \|\nabla u_t\|_{L^2}^2 + C \|\nabla d_t\|_{L^3}^2 \leq \frac{1}{6} \|\nabla u_t\|_{L^2}^2 + C \|\nabla d_t\|_{L^2} \|\nabla d_t\|_{H^1}.$$

Substituting these estimates of III_i into (35), for $i = 1, 2, \dots, 6$, we have

$$\begin{aligned} & \frac{d}{dt} \int \rho |u_t|^2 dx + \int |\nabla u_t|^2 dx \\ & \leq \|\sqrt{\rho} u_t\|_{L^2}^2 + \|\nabla u\|_{H^1}^2 + \|\nabla d_t\|_{L^2} \|\nabla d_t\|_{H^1} \\ & \leq \|\sqrt{\rho} u_t\|_{L^2}^2 + \|u\|_{L^r}^s + \|\nabla d\|_{L^r}^s + \|\nabla^2 d\|_{H^1}^2 + \|\nabla d_t\|_{L^2} \|\nabla d_t\|_{H^1} + 1, \end{aligned} \tag{36}$$

where we have used (5), (11) and (12).

Differentiating (4) with respect to t , multiplying the resulting equation by d_{tt} , integrating by parts over Ω , and using $\frac{\partial d_t}{\partial \nu} = 0$ on $\partial\Omega$, we obtain

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int |\nabla d_t|^2 dx + \int |d_{tt}|^2 dx & = \int \langle \partial_t (|\nabla d|^2 d - u \cdot \nabla d), d_{tt} \rangle dx \\ & \leq \|d_{tt}\|_{L^2} \|d_t\|_{L^6} \|\nabla d\|_{L^6}^2 + \|d_{tt}\|_{L^2} \|\nabla d_t\|_{L^3} \|\nabla d\|_{L^6} \\ & \quad + \|d_{tt}\|_{L^2} \|u\|_{L^6} \|\nabla d_t\|_{L^3} + \|d_{tt}\|_{L^2} \|u_t\|_{L^6} \|\nabla d\|_{L^3} \\ & \leq \frac{1}{2} \|d_{tt}\|_{L^2}^2 + C (\|\nabla d_t\|_{L^2} \|\nabla d_t\|_{H^1} + \|\nabla u_t\|_{L^2}^2 + \|\nabla d_t\|_{L^2}^2 + 1), \end{aligned}$$

where we have used Sobolev inequality, Hölder inequality, the interpolation inequality, (4), (5) and (32). This implies

$$\frac{d}{dt} \int |\nabla d_t|^2 dx + \int |d_{tt}|^2 dx \leq C (\|\nabla d_t\|_{L^2} \|\nabla d_t\|_{H^1} + \|\nabla u_t\|_{L^2}^2 + \|\nabla d_t\|_{L^2}^2 + 1). \tag{37}$$

Now we need to estimate $\|\nabla d_t\|_{H^1}$. In fact, by applying the standard H^2 -estimate on the equation (4) under the boundary condition (6), together with (4), (5), (32) and the interpolation inequality, we have

$$\begin{aligned} \|\nabla d_t\|_{H^1} &\lesssim \|\nabla d_t\|_{L^2} + \|d_{tt}\|_{L^2} + \|\partial_t(u \cdot \nabla d)\|_{L^2} + \|\partial_t(|\nabla d|^2 d)\|_{L^2} \\ &\lesssim \|\nabla d_t\|_{L^2} + \|d_{tt}\|_{L^2} + \|u_t\|_{L^6} \|\nabla d\|_{L^3} + \|u\|_{L^6} \|\nabla d_t\|_{L^3} \\ &\quad + \|d_t\|_{L^6} \|\nabla d\|_{L^6}^2 + \|\nabla d_t\|_{L^3} \|\nabla d\|_{L^6} \\ &\lesssim \|d_{tt}\|_{L^2} + \|\nabla u_t\|_{L^2} + \|\nabla d_t\|_{L^2}^{\frac{1}{2}} \|\nabla d_t\|_{H^1}^{\frac{1}{2}} + \|\nabla d_t\|_{L^2} + 1 \\ &\leq \frac{1}{2} \|\nabla d_t\|_{H^1} + C (\|d_{tt}\|_{L^2} + \|\nabla u_t\|_{L^2} + \|\nabla d_t\|_{L^2} + 1). \end{aligned}$$

Thus

$$\|\nabla d_t\|_{H^1} \lesssim \|d_{tt}\|_{L^2} + \|\nabla u_t\|_{L^2} + \|\nabla d_t\|_{L^2} + 1. \tag{38}$$

Substituting (38) into (37), and using Cauchy inequality, we obtain

$$\frac{d}{dt} \int |\nabla d_t|^2 dx + \int |d_{tt}|^2 dx \leq \frac{1}{2} \|d_{tt}\|_{L^2}^2 + C (\|\nabla u_t\|_{L^2}^2 + \|\nabla d_t\|_{L^2}^2 + 1).$$

Thus

$$\frac{d}{dt} \int |\nabla d_t|^2 dx + \frac{1}{2} \int |d_{tt}|^2 dx \leq C (\|\nabla u_t\|_{L^2}^2 + \|\nabla d_t\|_{L^2}^2 + 1). \tag{39}$$

Multiplying (36) by $2C$ and adding the resulting inequality into (39), applying (38), using (1), (5), and then employing Gronwall inequality, we obtain

$$\sup_{0 \leq t \leq T} \int (\rho |u_t|^2 + |\nabla d_t|^2) dx + \int_0^T \int_{\Omega} (|\nabla u_t|^2 + |d_{tt}|^2) dx dt \leq C. \tag{40}$$

To estimate $\nabla^3 d$ in $L_t^\infty L_x^2(\Omega \times [0, T])$, applying (5), (40) and the standard H^3 -estimate on the equation (19) under the boundary condition (6), we have

$$\begin{aligned} \|\nabla d\|_{H^2}^2 &\lesssim \|\nabla d_t\|_{L^2}^2 + \|\nabla(u \cdot \nabla d)\|_{L^2}^2 + \|\nabla(|\nabla d|^2 d)\|_{L^2}^2 + 1 \\ &\lesssim \|\nabla d_t\|_{L^2}^2 + \|\nabla d\|_{L^\infty}^2 (\|\nabla u\|_{L^2}^2 + \|\nabla^2 d\|_{L^2}^2) + \|\nabla d\|_{L^6}^6 + \int |u|^2 |\nabla^2 d|^2 dx + 1 \\ &\lesssim 1 + \|\nabla d\|_{L^\infty}^2 + \int |u|^2 |\nabla^2 d|^2 dx. \end{aligned} \tag{41}$$

For the last term on the right hand side of (41), using the interpolation inequality, and applying (5), we have

$$\begin{aligned} \int |u|^2 |\nabla^2 d|^2 dx &\leq \|u\|_{L^6}^2 \|\nabla^2 d\|_{L^3}^2 \lesssim \|\nabla u\|_{L^2}^2 \|\nabla^2 d\|_{L^2} \|\nabla^2 d\|_{H^1} \\ &\leq \epsilon \|\nabla d\|_{H^2}^2 + C_\epsilon. \end{aligned} \tag{42}$$

Substituting (42) into (41), and choosing ϵ sufficiently small, we have

$$\|\nabla d\|_{H^2}^2 \lesssim 1 + \|\nabla d\|_{L^\infty}^2. \tag{43}$$

Using the interpolation inequality again, together with (43), (4) and Young inequality, we have

$$\|\nabla d\|_{H^2}^2 \leq C + C \|\nabla d\|_{L^2}^{\frac{1}{2}} \|\nabla d\|_{H^2}^{\frac{3}{2}} \leq \frac{1}{2} \|\nabla d\|_{H^2}^2 + C,$$

which clearly yields that

$$\|\nabla d\|_{H^2} \leq C.$$

The proof is now complete. □

Corollary 2.6. *Under the same assumptions as in Lemma 2.5, we have for a.e. $t \in [0, T_*)$*

$$\|\nabla u\|_{H^1}(t) + \int_0^t \|u\|_{W^{2,6}}^2(s) ds \leq C, \text{ and } \int_0^t (\|\nabla^2 d_t\|_{L^2}^2 + \|\nabla^4 d\|_{L^2}^2)(s) ds \leq C. \tag{44}$$

Proof. By (11), we have

$$\begin{aligned} \|\nabla u\|_{H^1}^2 &\leq \|\rho u_t\|_{L^2}^2 + \|\rho u \cdot \nabla u\|_{L^2}^2 + \int |\nabla d|^2 |\nabla^2 d|^2 dx \\ &\leq \|u\|_{L^6}^2 \|\nabla u\|_{L^3}^2 + \|\nabla d\|_{L^6}^2 \|\nabla^2 d\|_{L^3}^2 + 1 \\ &\leq C \|\nabla u\|_{L^2} \|\nabla u\|_{H^1} + C \leq \frac{1}{2} \|\nabla u\|_{H^1}^2 + C, \end{aligned}$$

where we have used Hölder inequality, (3), the interpolation inequality, (5), (33) and Cauchy inequality. Thus,

$$\sup_{0 \leq t \leq T} \|\nabla u\|_{H^1} \leq C. \tag{45}$$

Similarly, we have

$$\begin{aligned} \|u\|_{W^{2,6}} &\leq \|\rho u_t\|_{L^6} + \|\rho u \cdot \nabla u\|_{L^6} + \|\nabla \cdot (\nabla d \otimes \nabla d)\|_{L^6} \\ &\leq \|u_t\|_{L^6} + \|u\|_{L^\infty} \|\nabla u\|_{L^6} + \|\nabla d\|_{L^\infty} \|\nabla^2 d\|_{L^6} \\ &\leq \|\nabla u_t\|_{L^2} + \|\nabla u\|_{H^1}^2 + 1, \end{aligned}$$

thus

$$\int_0^T \|u\|_{W^{2,6}}^2 dt \leq C,$$

where we have used (33) and (45).

It follows from (38) and (33) that

$$\int_0^T \|\nabla^2 d_t\|_{L^2}^2 dt \leq C. \tag{46}$$

Applying the standard H^4 -estimate to (4), we have

$$\begin{aligned} \|\nabla^4 d\|_{L^2}^2 &\leq \|\nabla^2 d_t\|_{L^2}^2 + \|\nabla^2(u \cdot \nabla d)\|_{L^2}^2 + \|\nabla^2(|\nabla d|^2 d)\|_{L^2}^2 + 1 \\ &\leq \|\nabla^2 d_t\|_{L^2}^2 + \|u\|_{L^\infty}^2 \|\nabla^3 d\|_{L^2}^2 + \|\nabla d\|_{L^\infty}^2 \|\nabla^2 u\|_{L^2}^2 + \|\nabla u\|_{L^6}^2 \|\nabla^2 d\|_{L^3}^2 + 1 \\ &\leq \|\nabla^2 d_t\|_{L^2}^2 + 1. \end{aligned}$$

Integrating this inequality over $[0, T]$, and using (46), we get

$$\int_0^T \|\nabla^4 d\|_{L^2}^2 dt \leq C.$$

□

Step 5. Estimate of $\nabla \rho$ in $L_t^\infty L_x^r$.

Lemma 2.7. *Let $0 < T_* < +\infty$ be the maximum time for the strong solution (ρ, u, d) to (1)-(6). If (7) and (1) hold, then for a.e. $t \in [0, T_*)$, we have*

$$\|\nabla \rho\|_{L^r}(t) + \int_0^t \|\nabla u\|_{H^2}^2 ds \leq C. \tag{47}$$

Proof. Using (3), we change (1) into this equation

$$\rho_t + u \cdot \nabla \rho = 0. \quad (48)$$

Differentiating (48) with respect to x , we have

$$\nabla \rho_t + \nabla u \cdot \nabla \rho + u \cdot \nabla \nabla \rho = 0. \quad (49)$$

Multiplying (49) by $r|\nabla \rho|^{r-2} \nabla \rho$, integrating by parts over Ω , and using the interpolation inequality and (5), we have

$$\frac{d}{dt} \|\nabla \rho\|_{L^r}^r \lesssim \|\nabla u\|_{L^\infty} \|\nabla \rho\|_{L^r}^r \lesssim \|\nabla u\|_{L^2}^{\frac{1}{4}} \|\nabla u\|_{W^{1,6}}^{\frac{3}{4}} \|\nabla \rho\|_{L^r}^r \lesssim \|\nabla u\|_{W^{1,6}}^{\frac{3}{4}} \|\nabla \rho\|_{L^r}^r. \quad (50)$$

By Gronwall inequality, together with (44), we have

$$\sup_{0 \leq t \leq T} \|\nabla \rho\|_{L^r} \leq C. \quad (51)$$

By (2) together with the H^3 -estimate for the Stokes equations, we have

$$\begin{aligned} \|\nabla u\|_{H^2}^2 &\lesssim \|\nabla(\rho u_t)\|_{L^2}^2 + \|\nabla(\rho u \cdot \nabla u)\|_{L^2}^2 + \|\nabla \nabla \cdot (\nabla d \otimes \nabla d)\|_{L^2}^2 \\ &\lesssim \|\nabla u_t\|_{L^2}^2 + \|\nabla \rho\|_{L^3}^2 \|u_t\|_{L^6}^2 + \|\nabla \rho\|_{L^3}^2 \|u\|_{L^\infty}^2 \|\nabla u\|_{L^6}^2 + \|\rho\|_{L^\infty}^2 \|\nabla u\|_{L^4}^4 \\ &\quad + \|\rho\|_{L^\infty}^2 \|u\|_{L^\infty}^2 \|\nabla^2 u\|_{L^2}^2 + \|\nabla d\|_{L^\infty}^2 \|\nabla^3 d\|_{L^2}^2 + \|\nabla^2 d\|_{L^4}^4 \\ &\lesssim \|\nabla u_t\|_{L^2}^2 + 1, \end{aligned}$$

where we have used Hölder inequality, Sobolev inequality, (3), (33), (44) and (51). This, together with (33), gives

$$\int_0^t \|\nabla u\|_{H^2}^2 \leq C.$$

The proof is now complete. \square

Step 6. Completion of proof of Theorem 1.3:

With the above established estimates, we obtain (2). This implies that T_* is not the maximum time of existence of strong solutions, which contradicts the definition of T_* . Therefore, (1) is false. The proof of Theorem 1.3 is now complete. \square

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